

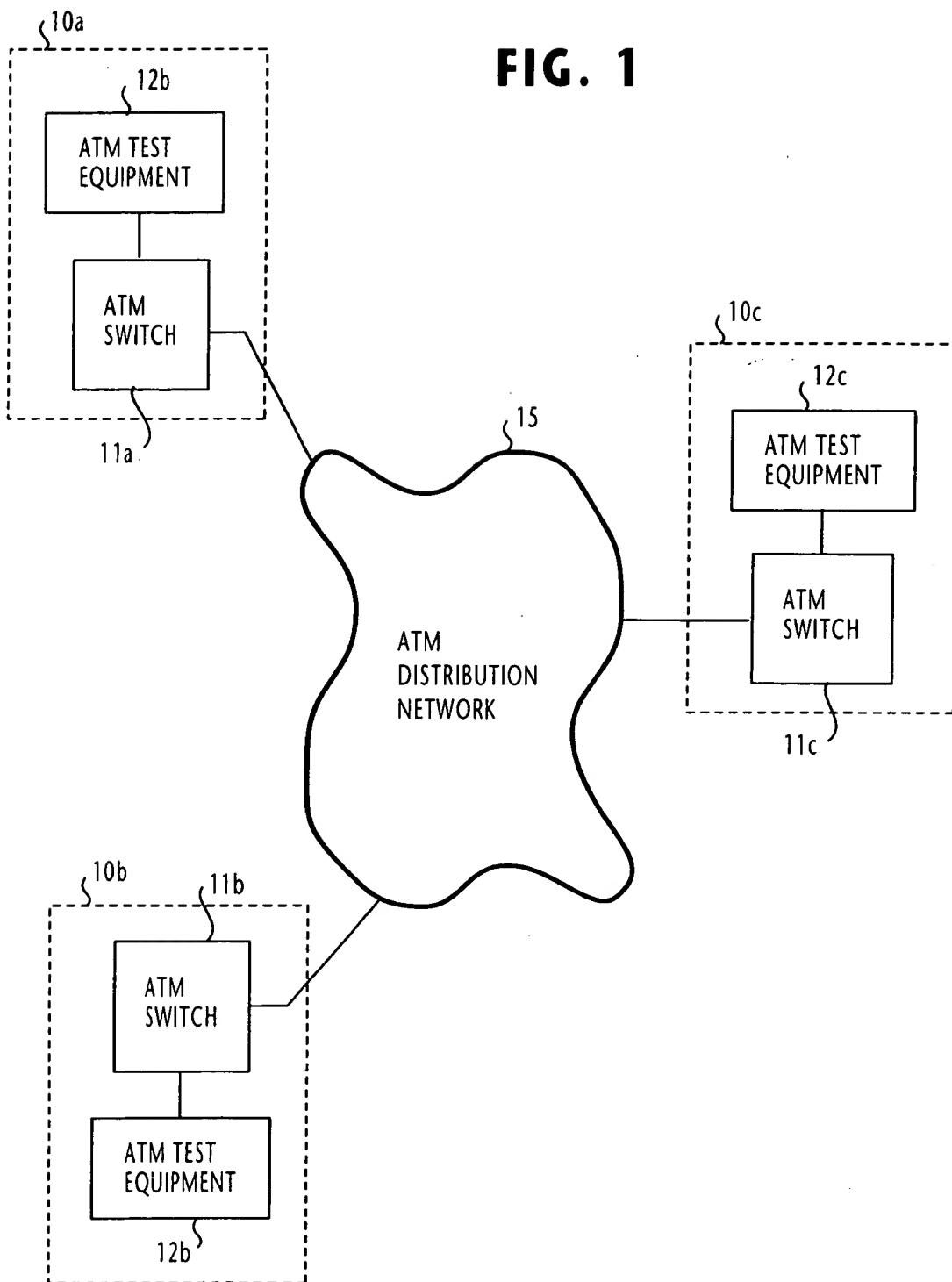
FIG. 1

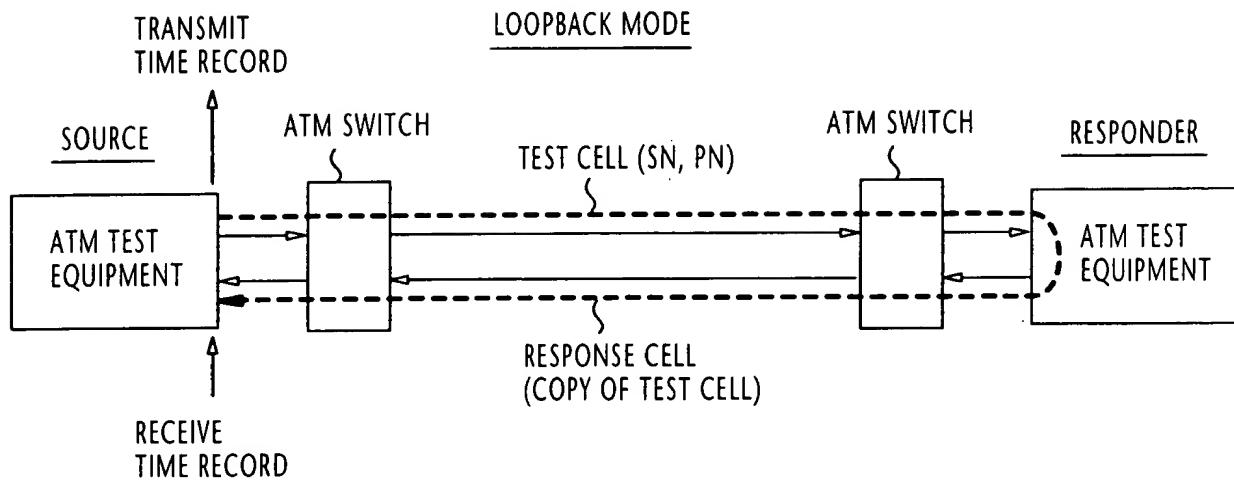
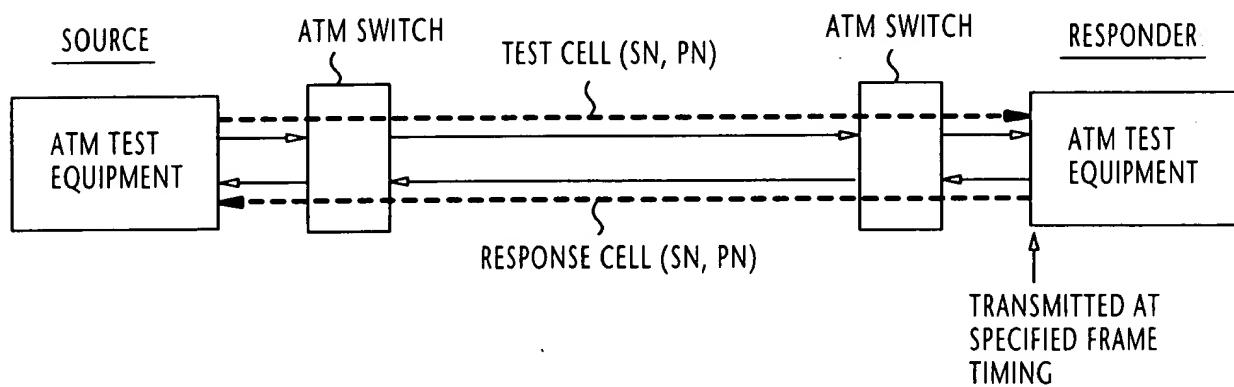
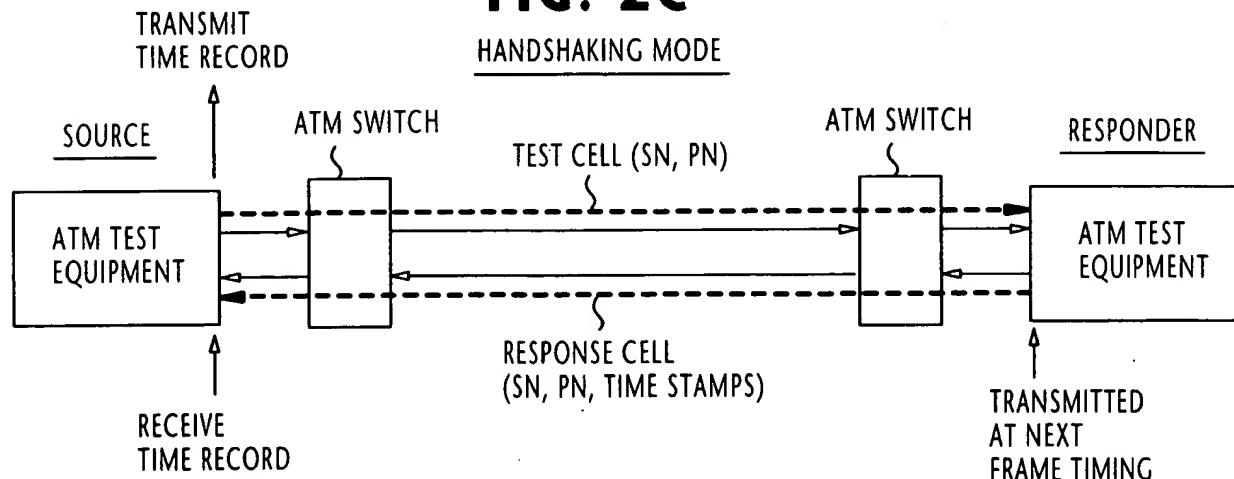
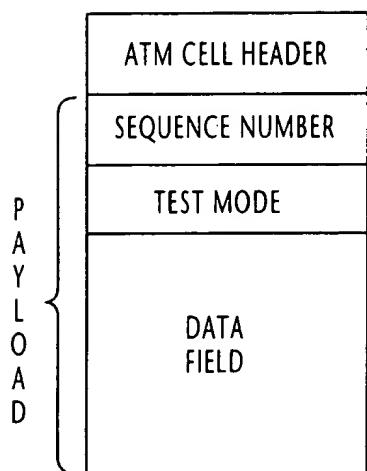
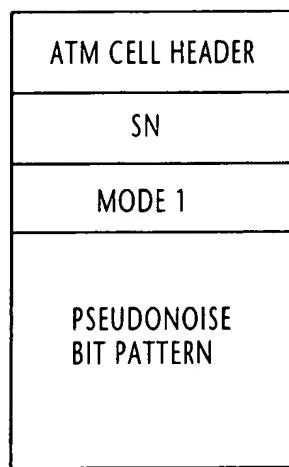
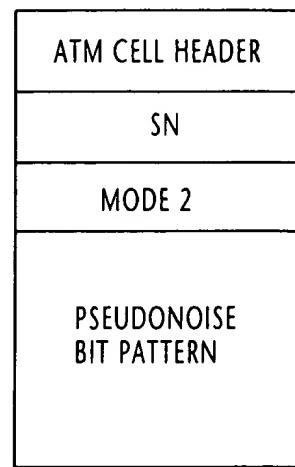
FIG. 2ALOOPBACK MODE**FIG. 2B**TWO-WAY MODE**FIG. 2C**HANDSHAKING MODE

FIG. 3A**FIG. 3B**

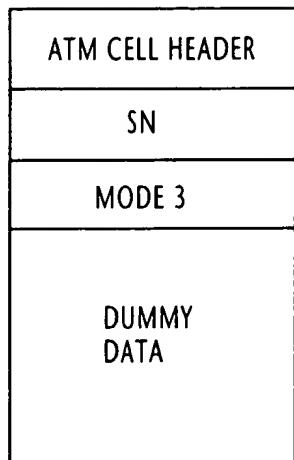
SOURCE AND RESPONDER
NODES (LOOPBACK MODE)

**FIG. 3C**

SOURCE AND RESPONDER
NODES (TWO-WAY MODE)

**FIG. 3D**

SOURCE NODE
(HANDSHAKING MODE)

**FIG. 3E**

RESPONDER NODE
(HANDSHAKING MODE)

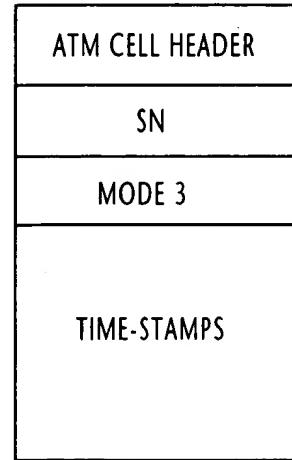
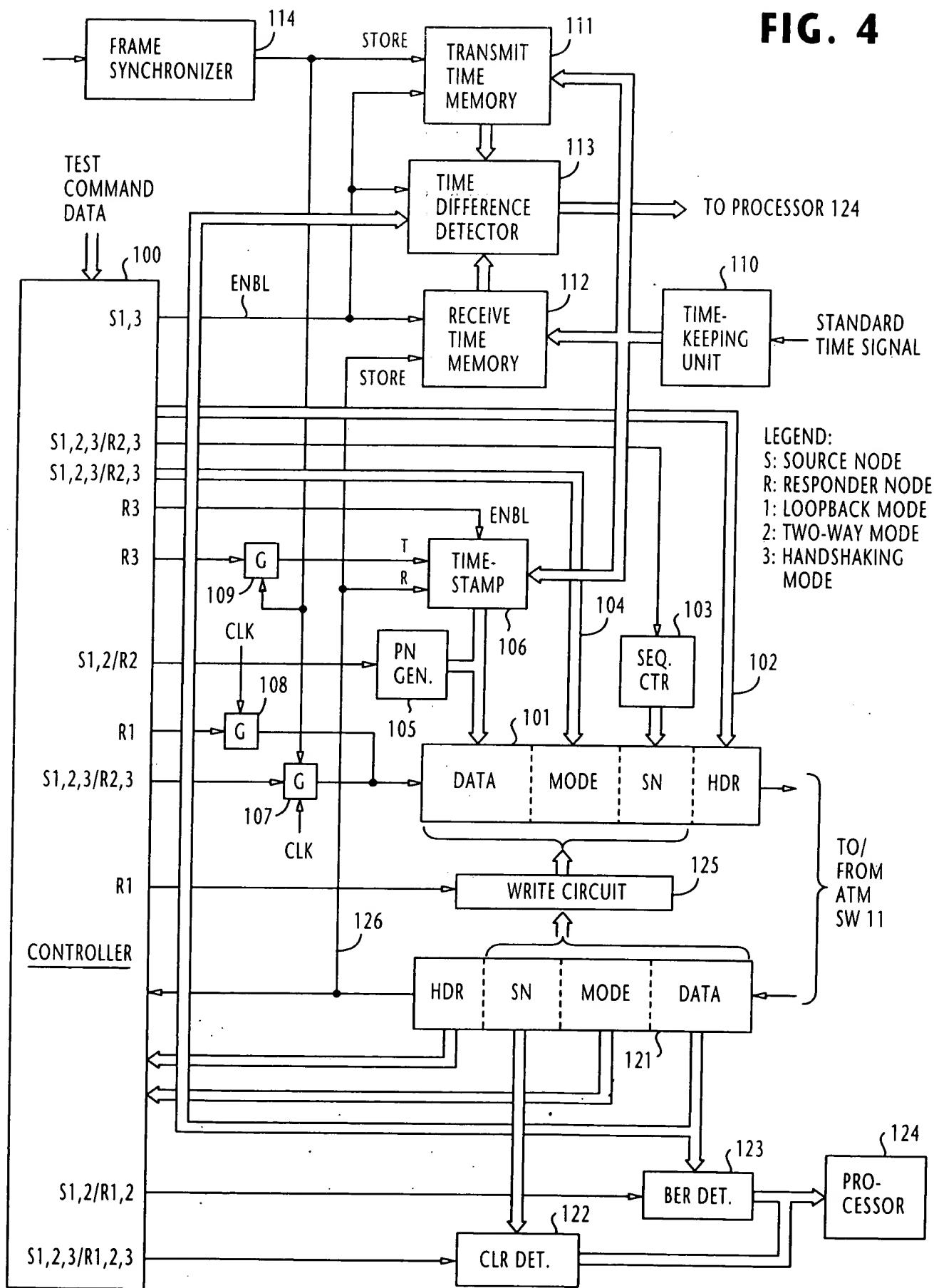
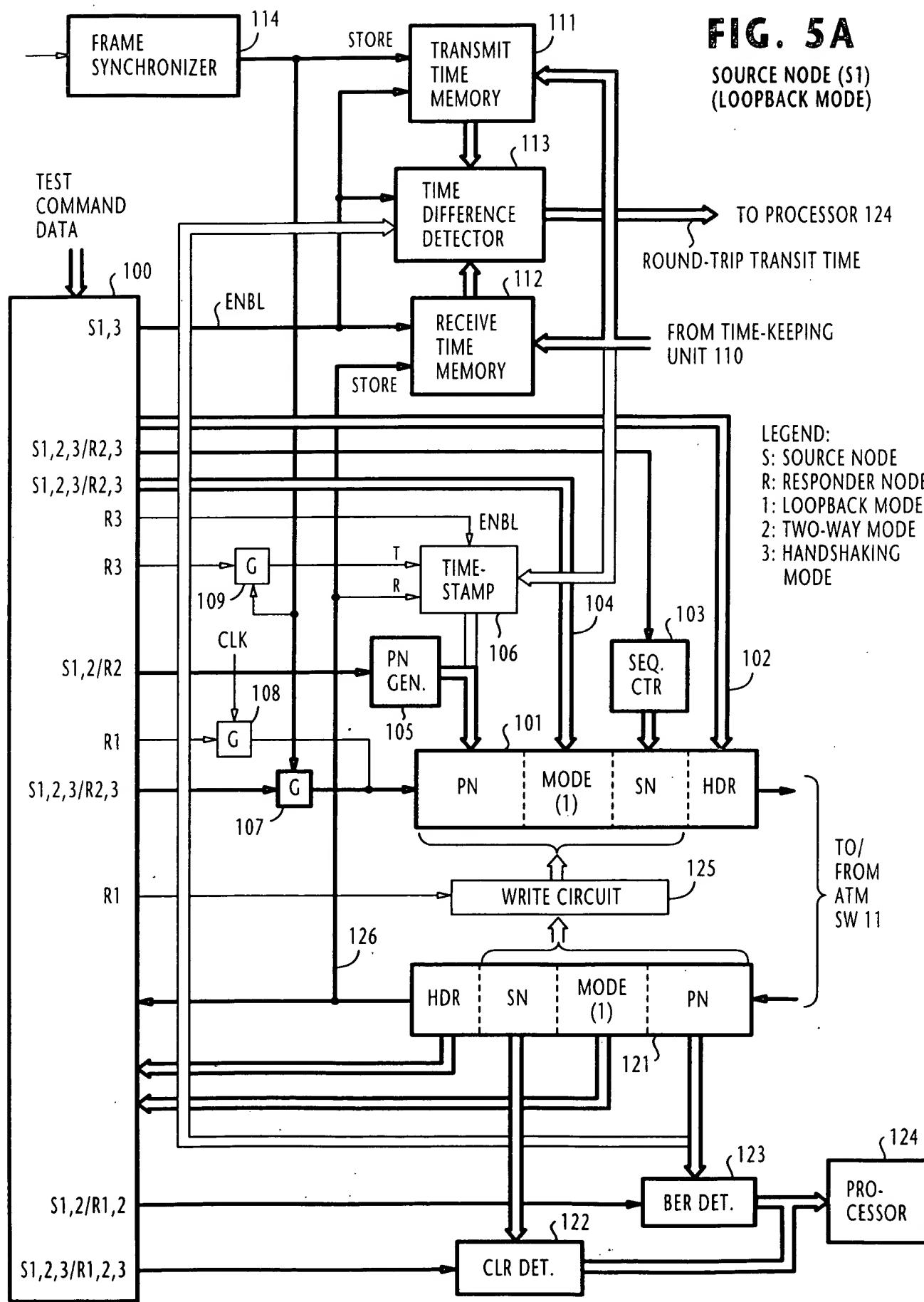
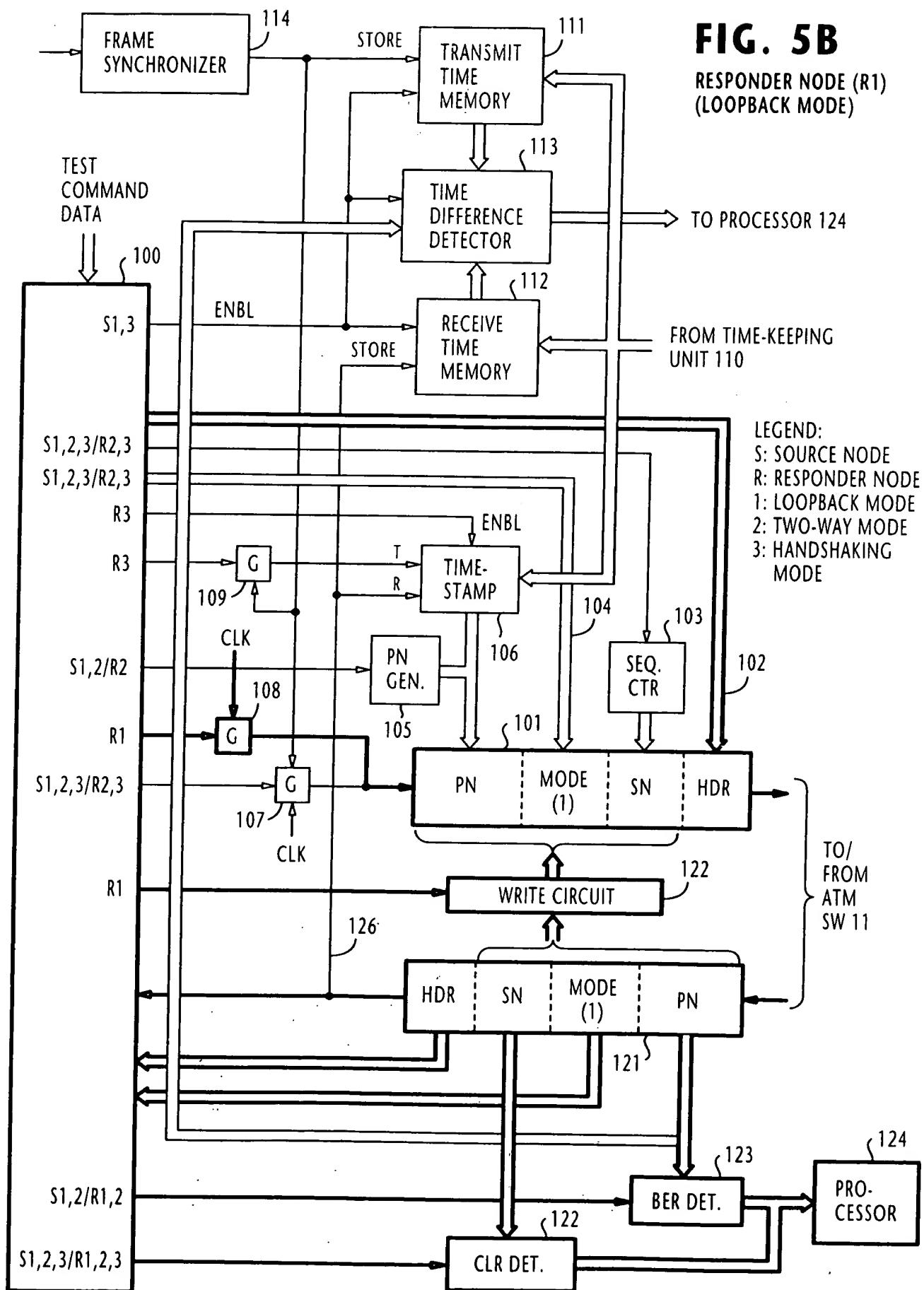
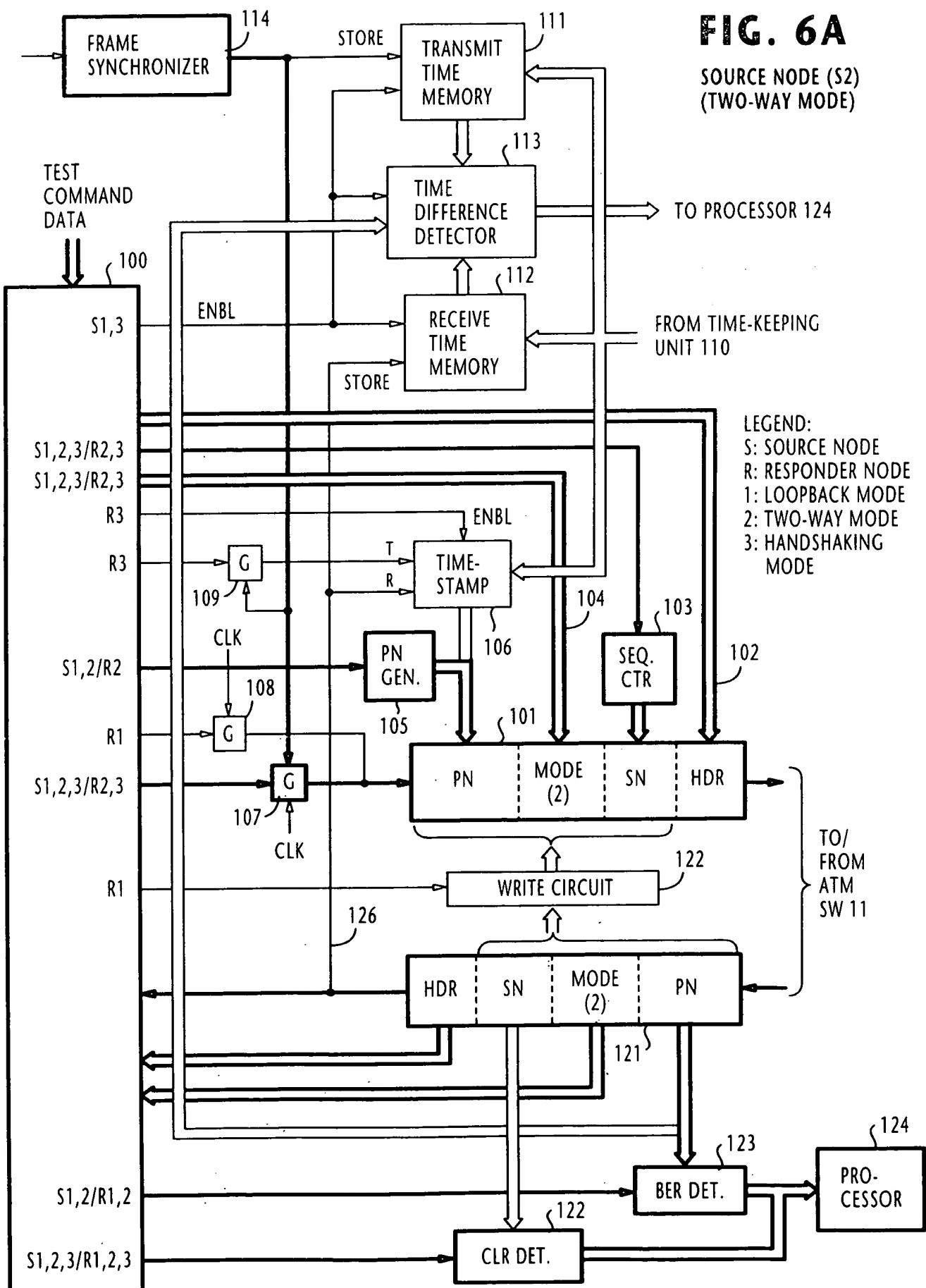


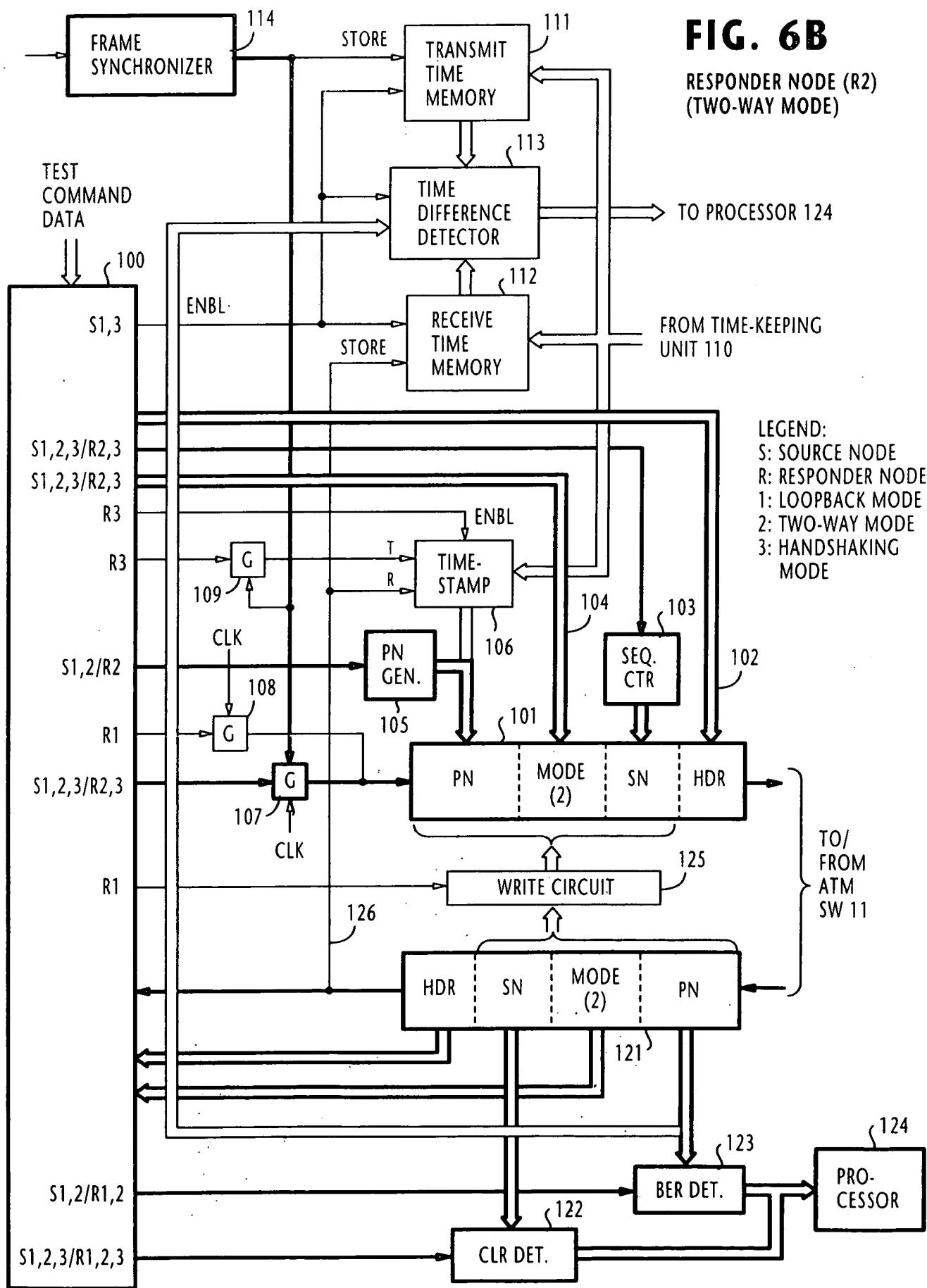
FIG. 4

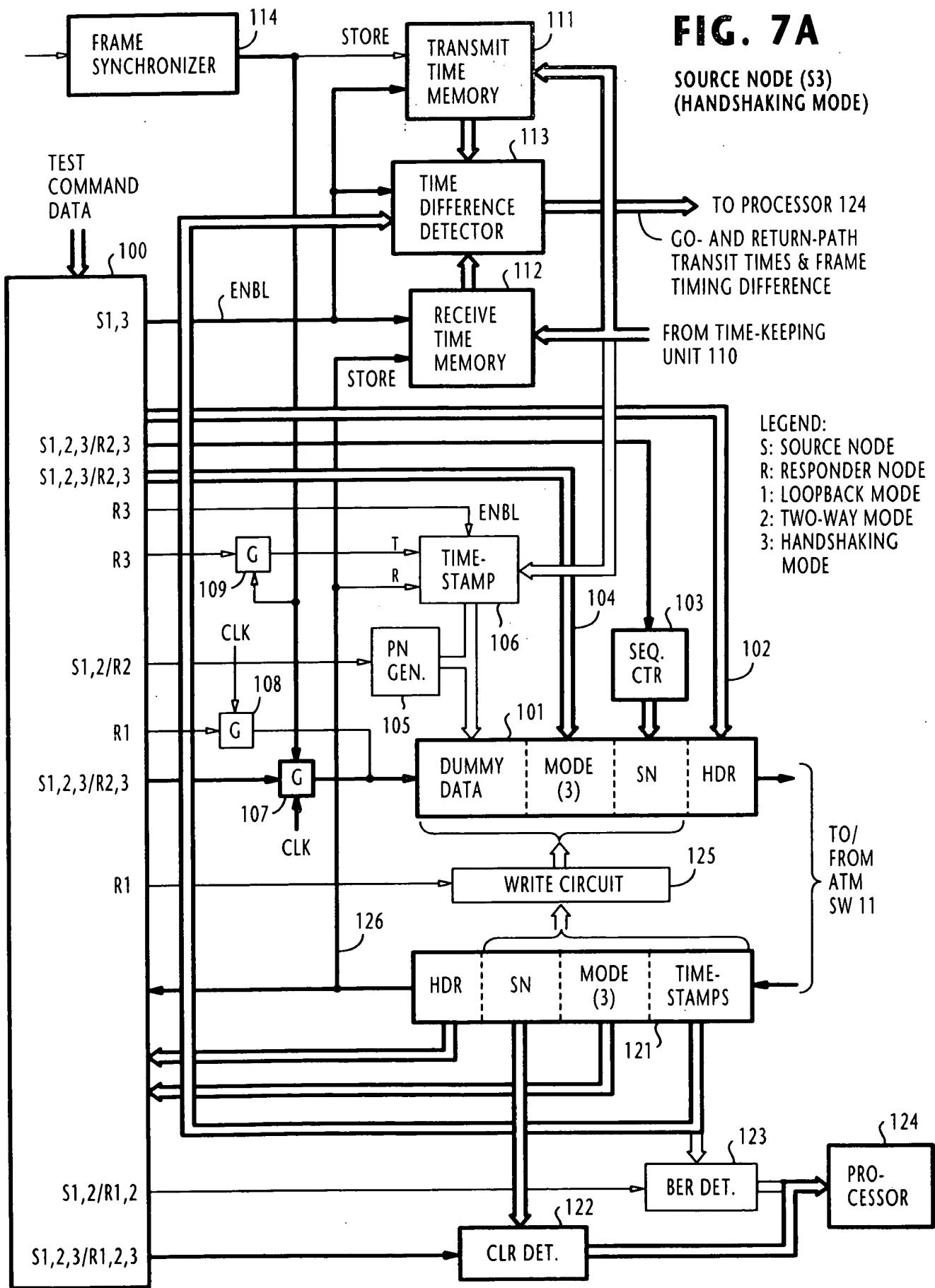












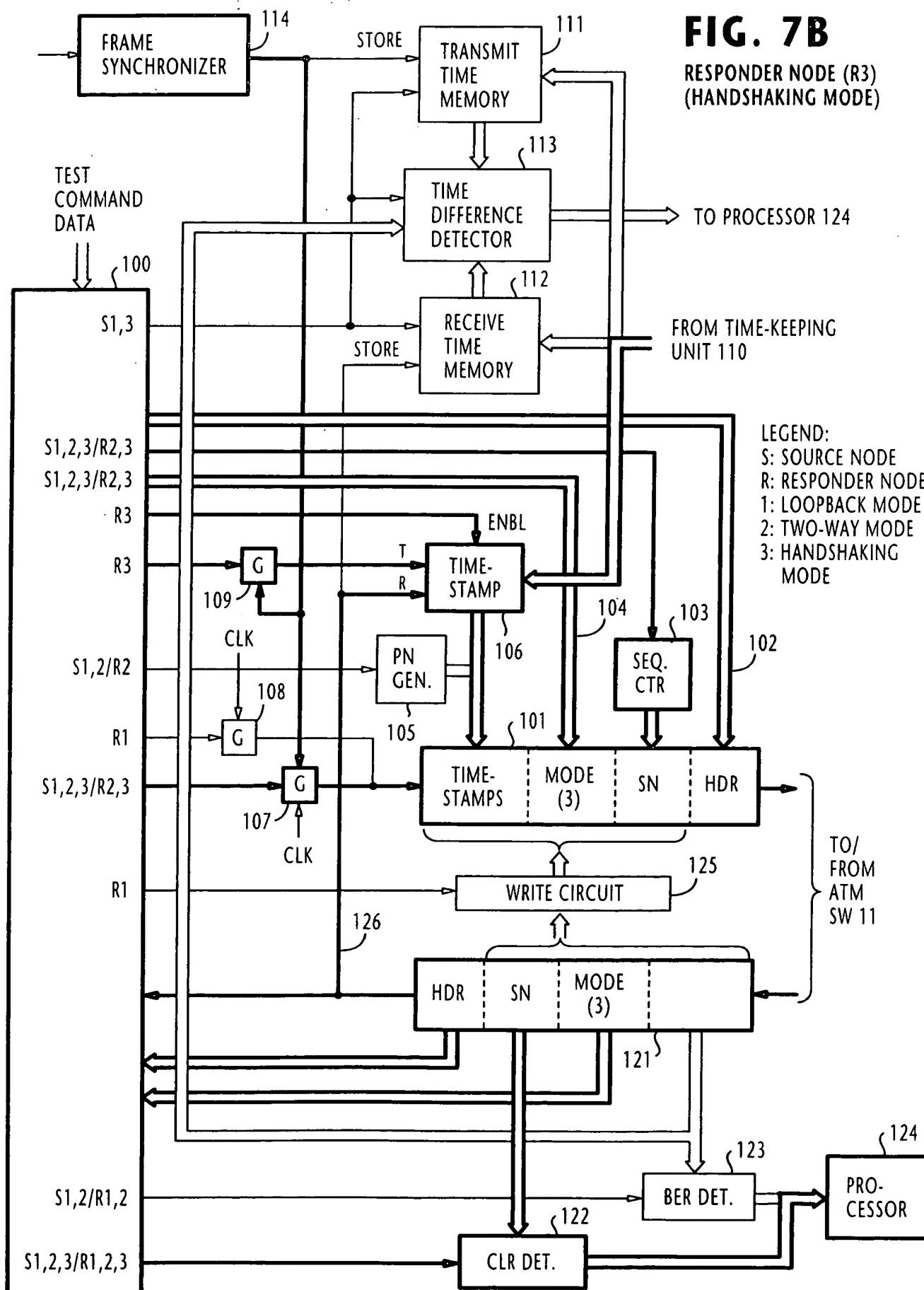


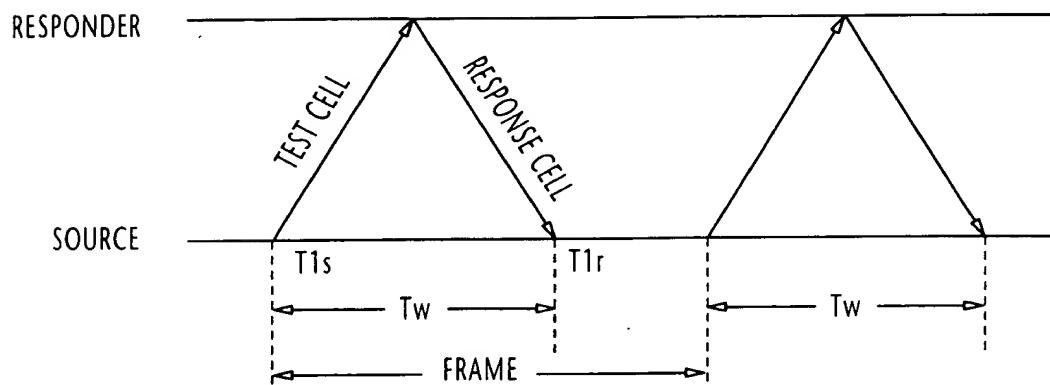
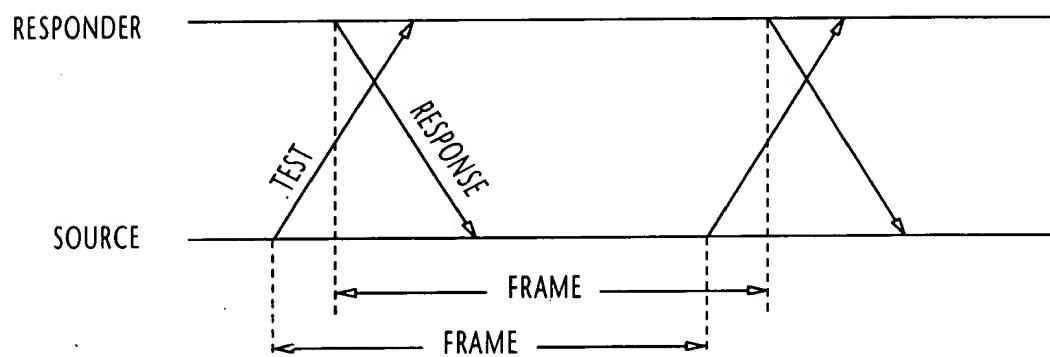
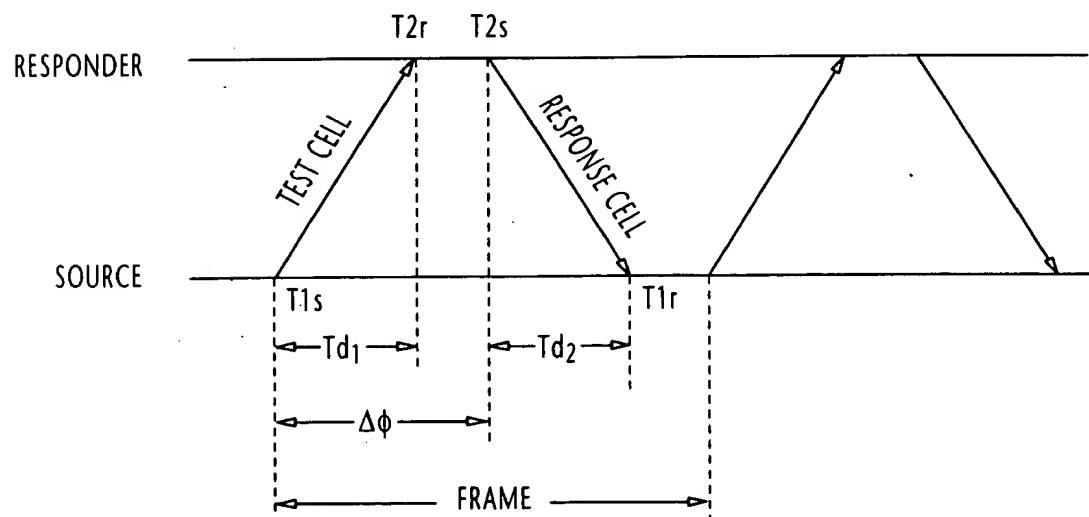
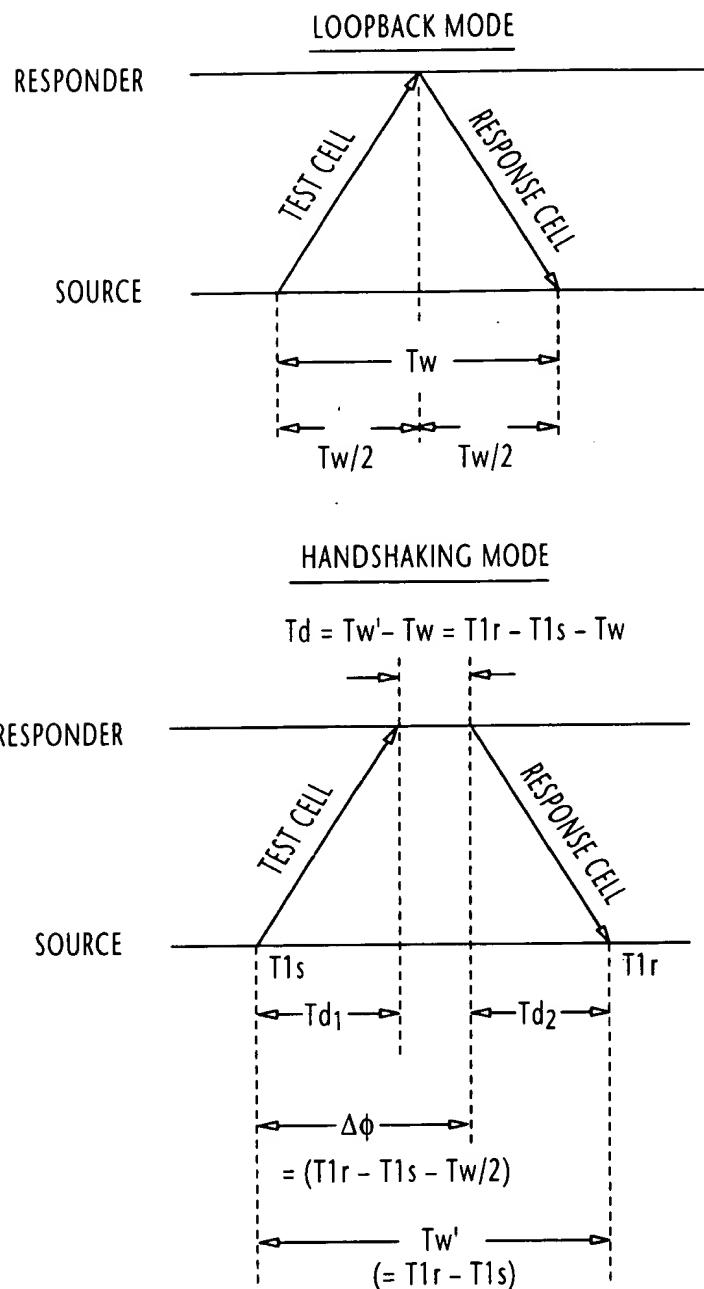
FIG. 8A LOOPBACK MODE**FIG. 8B** TWO-WAY MODE**FIG. 8C** HANDSHAKING MODE

FIG. 9

$$T_{d1} = \Delta\phi - T_d = \Delta\phi - (T_{1r} - T_{1s} - T_w)$$

$$T_{d2} = T_w' - \Delta\phi = T_{1r} - T_{1s} - \Delta\phi$$

FIG. 10